

QRs OF 3D LASER SCANNING AND IMAGING SYSTEM

S No	Specifications
<u>System Functionality</u>	
1.	System must provide automatic 3D Scanning with 360 degree horizontal by 300 degree or better vertical field of view
2.	Ranging Accuracy 4mm or better at 10 mtr 7mm or better at 20 mtr With user selectable resolution settings
3.	Option-I:- a) System must capture objects at minimum range of 0.65 mtr to 60 mtr or better b) System must support 150 Mega pixels or better Panoramic image full dome capture, HDR, LED flash calibrated spherical image/IR based imaging c) Data Acquisition rate must be minimum 3,50000 points per second or better. Option-II:- a) System must capture objects at minimum range of 0.65 mtr to 130 mtr or better from axis of scanner (Radial Range) b) System must support 400 Mega pixels or better Panoramic image full dome capture, HDR, calibrated spherical image/IR based imaging. c) Data Acquisition rate must be minimum 10,00000 points per second or better. (As per user requirement)
4.	System must use Waveform Digitization Technology for better results
5.	System must support at least IP54 rating for dust and water protection
6.	System must provide onsite registration, real time viewing & navigation of image during scan process
7.	System must operate on portable battery with minimum 3 hrs of operation or better per battery
8.	Must have scan time of roughly 4-5 minutes per position including HDR image capture
9.	System must support either onboard memory or external options like SD card industrial grade USB.
10.	System must provide data manipulation, visualisation and modelling capabilities such as creation of 2D drawing and creation of CAD objects

A series of handwritten signatures and initials in black ink, including names like 'Shy', 'Shz', 'Nay', 'A', 'Chy', 'a', 'De', 'Qs.', and 'Mm'.

S No	Specifications
11	System must support data registration, computation, analysis and modelling under one single software environment and in one single database upto the web publication phase, animation and 3 D modelling phase
12.	System must allow publication of point cloud into web-based format for online collaboration, support hyperlink, measurement, mark up inside Web browser. System should be simple to use and install and should not require server installation.
13.	System must come with Centralised Storage for high speed point cloud rendering with administrative privileges which allow a user to grant access to a particular project.
14.	System must be portable and easy to deploy preferably not more than 6kg.
15.	Capture instrument should support remote operation through Wi-Fi for laptop and mobile device operations.
16.	The Scanner shall be supplied with a Light weight Carbon Fibre Tripod, capable of handling 18Kg of Payload weight
17.	The transportation Box of the solution should be waterproof
18.	Software system must be able to handle unlimited size of point cloud database
19.	Software system must be client server based to allow a single storage of and dissemination of point cloud data
20.	System must provide Sophisticated Crash & Post Event Reconstruction Tools
21.	System must provide 2D and 3D viewing capability in synchronized views
22.	System must provide minimum three registration methods and algorithms that can be used independently or in conjunction, namely 1) cloud-to-cloud matching 2) Known targets and 3) Automatic Visual Registration Tools.
23.	System must provide Audit Logs for Evidence Integrity.
24.	System must be compatible with Major Point Cloud handling and Publishing Softwares and should be able to conduct two way communications.
25	System must provide the ability to register and superimpose internal images automatically and external images (3D Cubic Map and single camera image) on scanned data for photo-realistic presentation

Handwritten signatures and initials:
Smy Sha Mary Mary
↓
Eht
AS Qb M₁₂
&

S No	<u>Specifications</u>
26.	Provide various scene investigation tools like Bullet Trajectory, Animation for construction, Point Cloud overlay on images for measurement and analysis, View point analysis, Wizard for creating finished diagrams, Sketching mode
27.	Should support extraction of 2D drawings from 3D models and scanned data
28.	Should support direct import of .FLS, .3DD, ASCII point data (XYZ,SVY, PTS, PTX, TXT), Land XML, ZFS, ZFC, DBX format and support .imp format
29.	Should support direct export format ASCII point data (XYZ, SVY, PTS, PTX, TXT), DXF, Land XML, DBX format
30.	Must Provide 3D limit box to reduce point density
31.	Must provide automatic and manual point density control
32.	Must provide cloud to cloud registration capabilities
33.	Must support Dynamic level of detail management, displaying different levels of scanned data & 3D model for fast visualization
34.	Take measurement on scanned data, 3D models; slope distances; volumes and surface areas
35.	Must support visualization on mobile/tablet in both mode - online and offline
36.	Must support integration with Industrial GIS Platforms
37.	Must support integration with 3 D modelling software like sketch up Pro, AutoCAD
38.	Must support visualization with or without server
39.	Operating temperature for equipment minimum +5 to +40 Degrees Celsius
40.	Must be able to create a web share of the captured/Processed Data to be reviewed at any remote location on any normal configuration of Laptop/ Tablet online or offline.
41.	Laser Class-1 must comply IEC 60825-1:2014
42.	Laser used to scan should be human safe
43.	Software application must support Integrated Virtual reality mode for better visualization
44.	Point cloud processing software should support all formats of cloud irrespective of hardware make and model
45.	Output created by Software should be supported by all 3D Formatting tools. Auto desk, solid works, cyclone, sketch up, fusion 360
46.	Application should support registration of multiple captures/scans/images automatically
47.	Service / Support of the equipment should be provided on PAN India basis.

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S No	Specifications
48.	Training: The bidder shall arrange to provide Onsite training for Anti - Terrorism, VVIP Security Planning, Indoor and outdoor Crime scene scanning and shall essentially conduct a workshop for the same
49.	OEM Should essentially have a local office in India.



AC-II Radha Krishnan.K
NSG



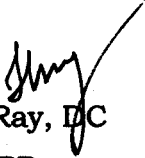
NB/SB Jeet Singh
Assam Rifles



INSP. Subhash Chand
BSF



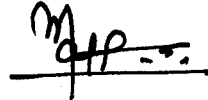
INSP. Sandesh Kumar
SSB



Tapas Ray, DC
ITBP



S.S. Sikarwar, DC
CISF



P.R. Jha, DC(Comn)
CRPF



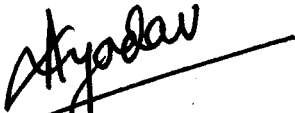
Rajnish Kumar
BPR&D



Harjinder Singh, DIG(Eqpt)
CRPF



D.S. Rawat, DIG (Comn)
CRPF

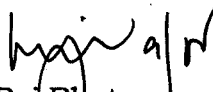


Ajay Kumar Yadav. IPS,
IGP(Comn &IT),CRPF



Md. Jawed Akhtar, IPS,
ADG (Work & Comn),CRPF

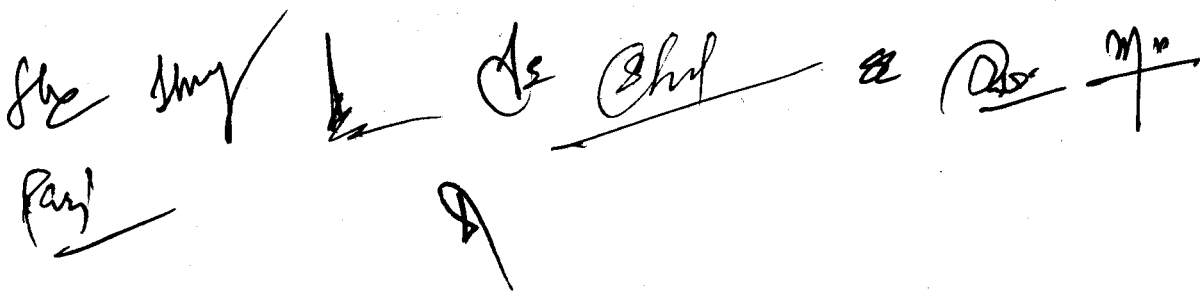
Approved/Not Approved



Rajeev Rai Bhatnagar, IPS
DG, CRPF

TRAIL DIRECTIVES OF 3D LASER SCANNING AND IMAGING SYSTEM

S N	Specifications	Trial Directives
System Functionality		
1.	System must provide automatic 3D Scanning with 360 degree horizontal by 300 degree or better vertical field of view	Firm will submit OEM Certificate
2.	Ranging Accuracy 4mm or better at 10 mtr 7mm or better at 20 mtr With user selectable resolution settings	Firm will submit OEM Certificate.
3.	Option-I:- a) System must capture objects at minimum range of 0.65 mtr to 60 mtr or better b) System must support 150 Mega pixels or better Panoramic image full dome capture, HDR, LED flash calibrated spherical image/IR based imaging c) Data Acquisition rate must be minimum 3,50000 points per second or better.	a) BOO will check practically. (b) & (c) Firm will submit OEM certificate.
	Option-II:- a) System must capture objects at minimum range of 0.65 mtr to 130 mtr or better from axis of scanner (Radial Range) b) System must support 400 Mega pixels or better Panoramic image full dome capture, HDR, calibrated spherical image/IR based imaging. c) Data Acquisition rate must be minimum 10,00000 points per second or better. (As per user requirement	a) BOO will check practically. (b) & (c) Firm will submit OEM certificate.
4.	System must use Waveform Digitization Technology for better results	Firm will submit OEM Certificate
5.	System must support at least IP54 rating for dust and water protection	Firm will submit OEM Certificate
6.	System must provide onsite registration, real time viewing & navigation of image during scan process	Board will check practically.



 The image contains several handwritten signatures and initials in black ink. At the top left, there is a signature that appears to be 'She May'. To its right is another signature that looks like 'As Chaf'. Further right is a signature that seems to be 'a' followed by a name that is partially obscured. At the bottom left, there is a signature that looks like 'Raj'. In the center, there is a large, stylized initial 'A'. At the bottom right, there is a signature that looks like 'M' followed by a name that is partially obscured.

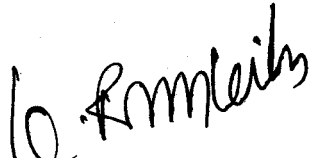
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7.	System must operate on portable battery with minimum 3 hrs of operation or better per battery	Board will check practically.
8.	Must have scan time of roughly 4-5 minutes per position including HDR image capture	Board will check practically.
9.	System must support either onboard memory or external options like SD card industrial grade USB.	Firm will submit OEM Certificate.
10.	System must provide data manipulation, visualisation and modelling capabilities such as creation of 2D drawing and creation of CAD objects	Board will check practically.
11	System must support data registration, computation, analysis and modelling under one single software environment and in one single database upto the web publication phase, animation and 3D modelling phase	Board will check practically.
12	System must allow publication of point cloud into web-based format for online collaboration, support hyperlink, measurement, mark up inside Web browser. System should be simple to use and install and should not require server installation.	Board will check practically.
13	System must come with Centralised Storage for high speed point cloud rendering with administrative privileges which allow a user to grant access to a particular project.	Board will check practically.
14	System must be portable and easy to deploy preferably not more than 6kg.	Board will check practically
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16	The Scanner shall be supplied with a Light weight Carbon Fibre Tripod, capable of handling 18Kg of Payload weight	Board will check practically
17	The Carrying Box of the solution should be waterproof	Firm will submit OEM Certificate
18	Software system must be able to handle unlimited size of point cloud database	Firm will submit OEM Certificate


Sh. Shing k. De *Chf* & *Qus* *M*
Ray


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21.	System must provide 2D and 3D viewing capability in synchronized views	Board will check practically
22.	System must provide minimum three registration methods and algorithms that can be used independently or in conjunction, namely 1) cloud-to-cloud matching 2) Known targets and 3) Automatic Visual Registration Tools.	Board will check practically and firm will also submit OEM certificate.
23.	System must provide Audit Logs for Evidence Integrity.	Board will check practically
24.	System must be compatible with Major Point Cloud handling and Publishing Softwares and should be able to conduct two way communications.	Board will check practically
25.	System must provide the ability to register and superimpose internal images automatically and external images (3D Cubic Map and single camera image) on scanned data for photo-realistic presentation	Board will check practically
26	Provide various scene investigation tools like Bullet Trajectory, Animation for construction, Point Cloud overlay on images for measurement and analysis, View point analysis, Wizard for creating finished diagrams, Sketching mode	Board will check practically.
27.	Should support extraction of 2D drawings from 3 D models and scanned data	Board will check practically
28.	Should support direct import of .FLS, .3DD, ASCII, point data (XYZ,SVY, PTS, PTX, TXT), Land XML, ZFS, ZFC, DBX format and support .imp format	Board will check practically and firm will also submit OEM Certificate
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39.	Operating temperature for equipment minimum +5 to +40 Degrees Celsius	Firm will submit certificate of any Govt. Lab or NABL or ILAC accredited laboratory or OEM certificate.
40.	Must be able to create a web share of the captured/Processed Data to be reviewed at any remote location on any normal configuration of Laptop/ Tablet online or offline.	Board will check practically
41.	Laser Class-1 must comply IEC 60825-1:2014	Firm will submit OEM Certificate & Data Sheet
42.	Laser used to scan should be human safe	Firm will submit OEM Certificate & Data Sheet
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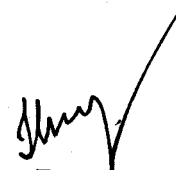
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AC-II Radha krishnan.K
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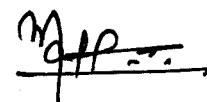

NB/SB Jeet singh
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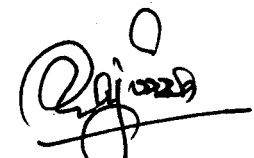

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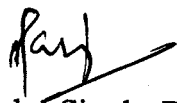

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SSB



Tapas Ray, DC
ITBP

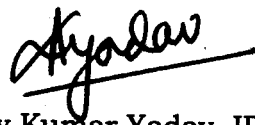

S.S. Sikarwar, DC
CISF



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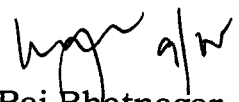

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